

Multi-Sensor RTK/PPP Module

WITH ANAVS[®] SENSOR FUSION FRAMEWORK

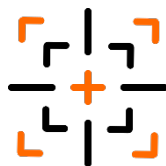
ALL-IN-VIEW GNSS Satellite tracking: multi-constellation, multi-frequency for fast convergence time

Multi-Sensor fusion on a single board for autonomous Vehicles, Robots, UAVs and Vessels

Interfaces to GNSS, INS, Odometry, Camera, Lidar, LPS and Barometer data



High rate solution output



Accurate position and attitude



Overcomes signal outages



Breakthrough price



Easy System Integration

SENSOR FUSION PERFORMANCE

Accurate RTK Positioning * (1σ):

Horizontal accuracy: 0.006 m + 1 ppm
Vertical accuracy: 0.010 m + 1 ppm

Accurate PPP Positioning * (1σ):

Horizontal accuracy: 0.20 m + 1 ppm
Vertical accuracy: 0.40 m + 1 ppm

Accurate Attitude * (1σ):

Accuracy: 0.25° (1m antenna spacing)

Velocity Accuracy: 0.03 m/s RMS

Time-Stamp Accuracy: 1 μ s RMS

Solution Output-Rate: up to 120 Hz

RTK Initialization *:

Initialization Time: < 7 sec

PPP Initialization *:

Initialization Time: < 4 min

* Depends on Environment and used GNSS-Antenna

GNSS FEATURES

GNSS Constellations:

Galileo, GPS, Glonass,
Beidou, SBAS (Egnos, WAAS, GAGAN)

GNSS Const. concurrent:

All

GNSS-Bands:

GPS: L1C/A, L1C, L1PY, L2C, L2P, L5
GLO: L1CA, L2CA, L2P, L3
GAL: E1, E5a, E5b, E5 AltBoc, E6
BDS: B1I, B1C, B2a, B2I, B3
QZSS: L1C/A, L1C, L2C, L5, L6

Channels: 448

GNSS data rate: max 100 Hz

Jamming detection: Yes

Timepulse-Output: Yes

STANDARD* IMU FEATURES

Linear acceleration meas. range:

+/- 16 g (configurable)

Angular rate meas. range:

+/- 4000 dps (configurable)

Linear acceleration sensitivity:

0.061 mg/LSB with +/- 2 g range

Angular rate sensitivity:

4.37 mdps/LSB bei +/- 125 dps range

Angular random walk (T=25°C):

0.21 deg/ \sqrt{h}

Bias stability:

3 degree/ hour (typical)

* more powerful IMUs can be chosen.

PROCESSOR PERFORMANCE

CPU: ARM 64Bit Quad-Core with 1.2 GHz

RAM: 1 to 4 Gbyte LPDDR2 RAM

Flash: 16 to 64 Gbyte

OS: Linux

ELECTRICAL & INTERFACES

Power Connector:

USB-C 5V or
Terminal connector up to 24V

Power Consumption:

Peak: 17.5 W (3.5A @ 5V)
Average: 10.5 W (2.1 A @ 5V)

Communication Interfaces:

Ethernet, WLAN, CAN, USB, LTE

Output format:

Standardized: NMEA format, ROS
Proprietary: ANavS binary format

ODOMETRY FEATURES

Performance:

Depends on resolution and quality of
user-based wheel/steering
measurements

Input/Output:

Configurable with DBC-files or
according to customer specification

Communication Interfaces:

CAN, Ethernet, USB

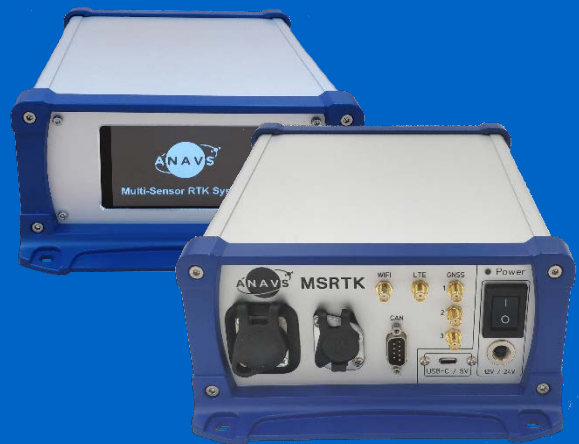
PRINTED CASING

Dimension:	128 x 119 x 55 mm
Weight:	250 g
Operating Temperature:	-25°C to +75°C
Display:	No



INDUSTRIAL CASING

Dimension:	294 x 195 x 95 mm
Weight:	1200 g
Operating Temperature:	-25°C to +75°C
Display:	Yes



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